

UMB CS622

Polynomial Time (P)

Wednesday November 10, 2021

$O(1) = O(\text{yeah})$
 $O(\log n) = O(\text{nice})$
 $O(n) = O(k)$
 $O(n^2) = O(\text{my})$
 $O(2^n) = O(\text{no})$
 $O(n!) = O(\text{mg})$
 $O(n^n) = O(\text{sh*t!})$

Announcements

- HW7 due tonight 11:59pm EST
- HW8 out tonight
- FYI: School holiday tomorrow (Thurs)

Last Time: Polynomial Time Complexity Class (**P**)

P is the class of languages that are decidable in polynomial time on a deterministic single-tape Turing machine. In other words,

$$\mathbf{P} = \bigcup_k \text{TIME}(n^k).$$

- Corresponds to “realistically” solvable problems:
 - Problems in **P** = “solvable” or “tractable”
 - Problems outside **P** = “unsolvable” or “intractable”

Let $t: \mathcal{N} \rightarrow \mathcal{R}^+$ be a function. Define the *time complexity class*, $\text{TIME}(t(n))$, to be the collection of all languages that are decidable by an $O(t(n))$ time Turing machine.

3 Problems in **P**

- A Graph Problem:

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

- A Number Problem:

$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$

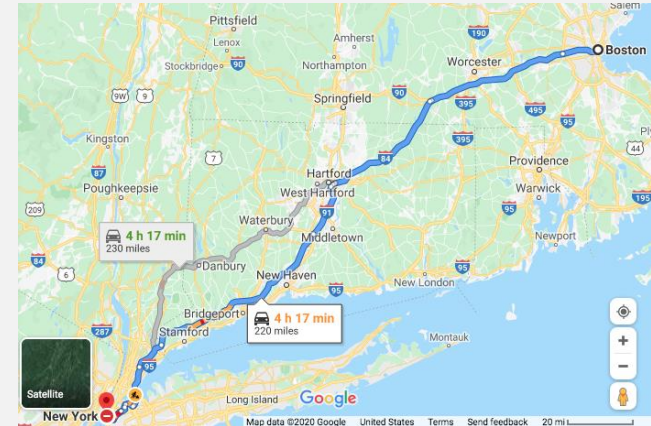
- A CFL Problem:

Every context-free language is a member of P

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

(A path is a sequence of nodes connected by edges)



- To prove that a language is in P ...
- ... we must construct a polynomial time algorithm deciding the lang
- Languages in P can still have non-polynomial (i.e., "brute force") algorithms:
 - check all possible paths, and see if any connect s to t
 - If $n = \#$ vertices, then $\#$ paths $\approx n^n$

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

of steps (worst case) ($n = \#$ nodes):

➤ Line 1: 1 step

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

of steps (worst case) ($n = \#$ nodes):

- Line 1: **1 step**
- Lines 2-3 (loop):
 - Steps/iteration (line 3): max # steps = max # edges = $O(n^2)$

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

of steps (worst case) ($n = \#$ nodes):

- Line 1: **1 step**
- Lines 2-3 (loop):
 - Steps/iteration (line 3): max # steps = max # edges = $O(n^2)$
 - # iterations (line 2): loop runs at most n times

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

of steps (worst case) ($n = \#$ nodes):

- Line 1: 1 step
- Lines 2-3 (loop):
 - Steps/iteration (line 3): max # steps = max # edges = $O(n^2)$
 - # iterations (line 2): loop runs at most n times
 - Total: $O(n^3)$

A Graph Theorem: $PATH \in P$

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

of steps (worst case) ($n = \#$ nodes):

- Line 1: **1 step**
- Lines 2-3 (loop):
 - Steps/iteration (line 3): max # steps = max # edges = $O(n^2)$
 - # iterations (line 2): loop runs at most n times
 - Total: $O(n^3)$
- Line 4: **1 step**

P is the class of languages that are decidable in polynomial time on a deterministic single-tape Turing machine. In other words,

$$P = \bigcup_k \text{TIME}(n^k).$$

A Graph Theorem: $PATH \in P$

$$PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t \}$$

PROOF A polynomial time algorithm M for $PATH$ operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
 3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

$$O(n^3)$$

(Breadth-first search)

of steps (worst case) ($n = \#$ nodes):

- Line 1: 1 step
 - Lines 2-3 (loop):
 - Steps/iteration (line 3): max # steps = max # edges = $O(n^2)$
 - # iterations (line 2): loop runs at most n times
 - Total: $O(n^3)$
 - Line 4: 1 step
- Total = $1 + 1 + O(n^3) = O(n^3)$

3 Problems in **P**

- A Graph Problem:

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

- A Number Problem:

$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$

- A CFL Problem:

Every context-free language is a member of P

A Number Theorem: $RELPRIME \in P$

$$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$$

- Two numbers are **relatively prime** if their gcd = 1
 - $\text{gcd}(x, y)$ = largest number that divides both x and y
 - E.g., $\text{gcd}(8, 12) = 4$
- Brute force exponential algorithm deciding $RELPRIME$:
 - Try all of numbers (up to x or y), see if it can divide both numbers
 - Why is this exponential?
 - HINT: What is a typical “representation” of numbers?
 - Answer: binary numbers
- A gcd algorithm that runs in poly time:
 - Euclid’s algorithm

A GCD Algorithm for: $RELPRIME \in P$

$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$

Modulo
(i.e., remainder)
cuts x (at least) in half

$15 \bmod 8 = 7$
 $17 \bmod 8 = 1$

Cutting x in half
every step requires:
 $\log x$ steps

The Euclidean algorithm E is as follows.

$E =$ “On input $\langle x, y \rangle$, where x and y are natural numbers in binary:

1. Repeat until $y = 0$:
2. Assign $x \leftarrow x \bmod y$.
3. Exchange x and y .
4. Output x .”

$O(n)$

Each number is
cut in half every
other iteration

Total run time (assume $x > y$): $2 \log x = 2 \log 2^n = O(n)$,
where $n =$ number of binary digits in (ie length of) x

3 Problems in **P**

- A Graph Problem:

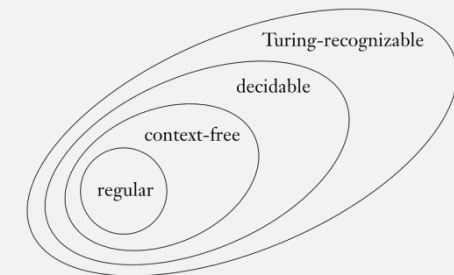
$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

- A Number Problem:

$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$

- A CFL Problem:

Every context-free language is a member of P



Review: HW5, Problem 4-1

Prove: the context-free oval is completely contained inside the decidable oval

- I.e., Every context-free language (CFL) is also a decidable language

Proof Plan:

- To prove that a language is decidable ... we must construct a decider for it
- To show that every CFL is decidable, we show how to construct a decider for any CFL

To construct our decider, we use the following things learned in this course:

- A language is a set of strings
- A CFL L is a language that ... has a CFG (G) and a PDA (P), where:
 - $w \in L \Leftrightarrow G$ generates w , or
 - $w \in L \Leftrightarrow P$ accepts w
- A decider (M) for a CFL L is a TM such that, on input w :
 - M accepts $w \Leftrightarrow G$ generates w , or
 - M accepts $w \Leftrightarrow P$ accepts w

Review: A Decider for Any CFL (HW5)

Given any CFL L , with CFG G , the following decider M_G decides L :

$M_G =$ “On input w :

1. Run TM S on input $\langle G, w \rangle$.
2. If this machine accepts, *accept*; if it rejects, *reject*.”

$S =$ “On input $\langle G, w \rangle$, where G is a CFG and w is a string:

1. Convert G to an equivalent grammar in Chomsky normal form.
2. List all derivations with $2n - 1$ steps, where n is the length of w ; except if $n = 0$, then instead list all derivations with one step.
3. If any of these derivations generate w , *accept*; if not, *reject*.”

S is a decider for: $A_{CFG} = \{ \langle G, w \rangle \mid G \text{ is a CFG that generates string } w \}$

A Decider for Any CFL: Running Time

Given any CFL L , with CFG G the following decider M_G decides L :

$M_G =$ “On input w :

1. Run TM S on input $\langle G, w \rangle$.
2. If this machine accepts, *accept*; if it rejects, *reject*.”

Worst case:
 $|R|^{2n-1}$ steps = $O(2^n)$
(R = set of rules)

$S =$ “On input $\langle G, w \rangle$, where G is a CFG and w is a string:

1. Convert G to an equivalent grammar in Chomsky normal form.
2. List all derivations with $2n - 1$ steps, where n is the length of w ; except if $n = 0$, then instead list all derivations with one step.
3. If any of these derivations generate w , *accept*; if not, *reject*.”

This algorithm runs in exponential time

S is a decider for: $A_{CFG} = \{ \langle G, w \rangle \mid G \text{ is a CFG that generates string } w \}$

A CFL Theorem: Every context-free language is a member of P

- Given a CFL, we must construct a decider for it ...
- ... that runs in polynomial time

Dynamic Programming

- Keep track of partial solutions, and re-use them
- For CFG problem, instead of re-generating entire string ...
 - ... keep track of substrings generated by each variable Dynamic programming

$S =$ “On input $\langle G, w \rangle$, where G is a CFG and w is a string:

1. Convert G to an equivalent grammar in Chomsky normal form.
2. List all derivations with $2n - 1$ steps, where n is the length of w ; except if $n = 0$, then instead list all derivations with one step.
3. If any of these derivations generate w , *accept*; if not, *reject*.”

This duplicates a lot of work because many strings might have have the same first few derivations steps

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating variables in a table

Substring end char

	b	a	a	b	a
b					
a					
a					
b					
a					

Substring start char

CFL Dynamic Programming Example

- Chomsky Grammar G :
 - $S \rightarrow AB \mid BC$
 - $A \rightarrow BA \mid a$
 - $B \rightarrow CC \mid b$
 - $C \rightarrow AB \mid a$
- Example string: **baaba**
- Store every partial string and their generating variables in a table

Substring end char

	b	a	a	b	a
b	vars for "b"	vars for "ba"	vars for "baa"	...	
a		vars for "a"	vars for "aa"	vars for "aab"	
a			...		
b					
a					

Substring start char

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating variables in a table

Algo:

- For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table

Substring end char

	b	a	a	b	a
b	vars for "b"	vars for "ba"	vars for "baa"	...	
a		vars for "a"	vars for "aa"	vars for "aab"	
a			...		
b					
a					

Substring start char

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating variables in a table

Algo:

- For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table

Substring end char

	b	a	a	b	a
b	B				
a		A,C			
a			A,C		
b				B	
a					A, C_4

Substring start char

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating variables in a table

Algo:

- For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table
- For each substring s ($\text{len} > 1$):
 - For each split of substring s into x,y :
 - For each rule of shape $A \rightarrow BC$:
 - Use table to check if B generates x and C generates y

Substring end char

	b	a	a	b	a
b	B				
a		A,C			
a			A,C		
b				B	
a					A,C ₇₅

Substring start char

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating

Algo:

- For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table
- For each substring s :
 - For each split of substring s into x,y :
 - For each rule of shape $A \rightarrow BC$:
 - use table to check if B

Substring end char

	b	a	a
b	B		
a		A,C	
a			A,C
b			
a			

Substring start char

For substring "ba", split into "b" and "a":

- For rule $S \rightarrow AB$
 - Does A generate "b" and B generate "a"?
 - NO
- For rule $S \rightarrow BC$
 - Does B generate "b" and C generate "a"?
 - YES
- For rule $A \rightarrow BA$
 - Does B generate "b" and A generate "a"?
 - YES
- For rule $B \rightarrow CC$
 - Does C generate "b" and C generate "a"?
 - NO
- For rule $C \rightarrow AB$
 - Does A generate "b" and B generate "a"?
 - NO

CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating

Algo:

- For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table
- For each substring s :
 - For each split of substring s into x,y :
 - For each rule of shape $A \rightarrow BC$:
 - use table to check if B

For substring "ba", split into "b" and "a":

- For rule $S \rightarrow AB$
 - Does A generate "b" and B generate "a"?
 - NO
- For rule $S \rightarrow BC$
 - Does B generate "b" and C generate "a"?
 - YES
- For rule $A \rightarrow BA$
 - Does B generate "b" and A generate "a"?
 - YES
- For rule $B \rightarrow CC$
 - Does C generate "b" and C generate "a"?
 - NO
- For rule $C \rightarrow AB$
 - Does A generate "b" and B generate "a"?
 - NO

Substring end char

	b	a	a
b	B	S,A	
a		A,C	
a			A,C
b			
a			

Substring start char



CFL Dynamic Programming Example

- Chomsky Grammar G :

- $S \rightarrow AB \mid BC$
- $A \rightarrow BA \mid a$
- $B \rightarrow CC \mid b$
- $C \rightarrow AB \mid a$

- Example string: **baaba**

- Store every partial string and their generating variables in a table

Algo:

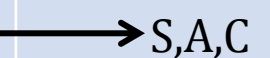
- For each char, var ...
 - For each single char c and var A :
 - If $A \rightarrow c$ is a rule, add A to table
 - For each substring s :
 - For each substring, split, rule ...
 - For each split of substring s into x,y :
 - For each rule of shape $A \rightarrow BC$:
 - Use table to check if B generates x and C generates y

Substring end char

Substring start char

	b	a	a	b	a
b	B	S,A			S,A,C
a		A,C	B	B	S,A,C
a			A,C	S,C	B
b				B	S,A
a					A,C

If S is here, accept



A CFG Theorem: Every context-free language is a member of P

$D =$ “On input $w = w_1 \cdots w_n$:

1. For $w = \varepsilon$, if $S \rightarrow \varepsilon$ is a rule, *accept*; else, *reject*. $\llbracket w = \varepsilon$ case \rrbracket
2. For $i = 1$ to n : $O(n)$ \llbracket examine each substring of length 1 \rrbracket
3. For each variable A : $\#vars$
4. Test whether $A \rightarrow b$ is a rule, where $b = w_i$. $\#vars * n = O(n)$
5. If so, place A in $table(i, i)$.
6. For $l = 2$ to n : $O(n)$ $\llbracket l$ is the length of the substring \rrbracket
7. For $i = 1$ to $n - l + 1$: $O(n)$ $\llbracket i$ is the start position of the substring \rrbracket
8. Let $j = i + l - 1$. $\llbracket j$ is the end position of the substring \rrbracket
9. For $k = i$ to $j - 1$: $O(n)$ $\llbracket k$ is the split position \rrbracket
10. For each rule $A \rightarrow BC$: $\#rules$
11. If $table(i, k)$ contains B and $table(k + 1, j)$ contains C , put A in $table(i, j)$. $\#rules * O(n) * O(n) * O(n) = O(n^3)$
12. If S is in $table(1, n)$, *accept*; else, *reject*.

Annotations:

- For each:
 - char
 - var
- For each:
 - substring
 - split
 - rule

Total: $O(n^3)$


(This is also known as the Earley parsing algorithm)

Summary: 3 Problems in **P**

- A Graph Problem:

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

“search” problem



- A Number Problem:

$RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$

- A CFL Problem:

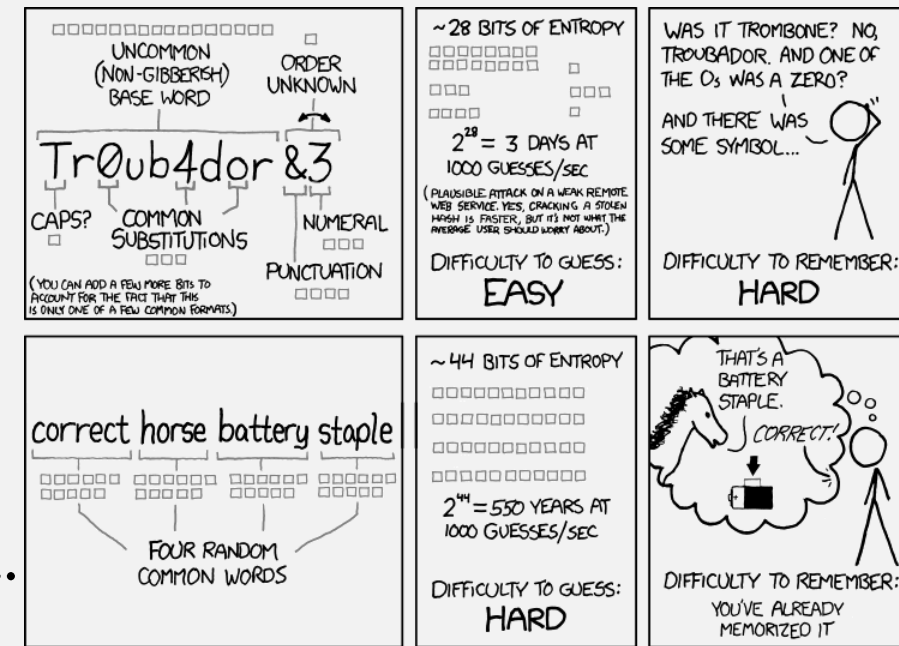
Every context-free language is a member of P

Search vs Verification

- Search problems are often **unsolvable**
- But, verification of search results is usually **solvable**

EXAMPLES

- Factoring
 - **Unsolvable:** Find factors of 8633
 - **Solvable:** Verify 89 and 97 are factors of 8633
- Passwords
 - **Unsolvable:** Find my umb.edu password
 - **Solvable:** Verify whether my umb.edu password is ...
 - “correct horse battery staple”



THROUGH 20 YEARS OF EFFORT, WE'VE SUCCESSFULLY TRAINED EVERYONE TO USE PASSWORDS THAT ARE HARD FOR HUMANS TO REMEMBER, BUT EASY FOR COMPUTERS TO GUESS.

The *PATH* Problem

$PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t\}$

- It's a **search** problem:
 - Exponential time (brute force) algorithm (n^n):
 - Check all possible paths and see if any connects s and t
 - Polynomial time algorithm:
 - Do a breadth-first search (roughly), marking “seen” nodes as we go

PROOF A polynomial time algorithm M for *PATH* operates as follows.

$M =$ “On input $\langle G, s, t \rangle$, where G is a directed graph with nodes s and t :

1. Place a mark on node s .
2. Repeat the following until no additional nodes are marked:
 3. Scan all the edges of G . If an edge (a, b) is found going from a marked node a to an unmarked node b , mark node b .
4. If t is marked, *accept*. Otherwise, *reject*.”

Verifying a *PATH*

$PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t \}$

The **verification** problem:

- Given some path p in G , check that it is a path from s to t
- Let m = longest possible path = # edges in G

NOTE: extra argument p

Verifier V = On input $\langle G, s, t, p \rangle$, where p is some set of edges:

1. Check some edge in p has “from” node s ; mark and set it as “current” edge
 - Max steps = $O(m)$
2. **Loop:** While there remains unmarked edges in p :
 1. Find the “next” edge in p , whose “from” node is the “to” node of “current” edge
 2. If found, then mark that edge and set it as “current”, else reject
 - Each loop iteration: $O(m)$
 - # loops: $O(m)$
 - Total looping time = $O(m^2)$
3. Check “current” edge has “to” node t ; if yes accept, else reject

- Total time = $O(m) + O(m^2) = O(m^2)$ = polynomial in m

PATH can be verified
in polynomial time

Verifiers, Formally

$PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph that has a directed path from } s \text{ to } t \}$

A *verifier* for a language A is an algorithm V , where

$A = \{ w \mid V \text{ accepts } \langle w, c \rangle \text{ for some string } c \}$ *certificate, or proof*

extra argument:
can be any string that helps
to find a result in poly time
(is often just a result itself)

We measure the time of a verifier only in terms of the length of w , so a *polynomial time verifier* runs in polynomial time in the length of w . A language A is *polynomially verifiable* if it has a polynomial time verifier.

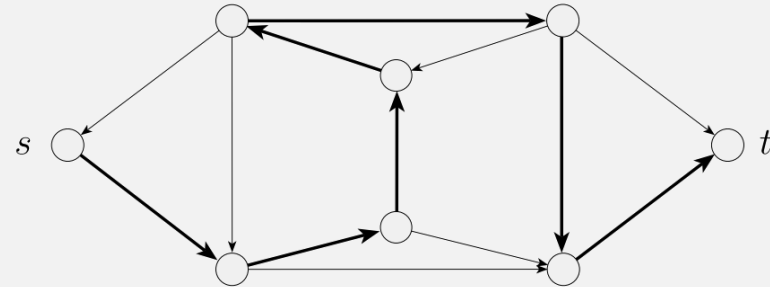
- NOTE: a cert c must be at most length n^k , where $n = \text{length of } w$
 - Why?

So $PATH$ is polynomially verifiable

The *HAMPATH* Problem

$HAMPATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t\}$

- A Hamiltonian path goes through every node in the graph



- The **Search** problem:
 - Exponential time (brute force) algorithm:
 - Check all possible paths and see if any connect s and t using all nodes
 - Polynomial time algorithm:
 - We don't know if there is one!!!
- The **Verification** problem:
 - Still $O(m^2)$!
 - *HAMPATH* is polynomially verifiable, but not polynomially decidable ⁸⁹

The class **NP**

DEFINITION

NP is the class of languages that have polynomial time verifiers.

- *PATH* is in **NP**, and **P**
- *HAMPATH* is in **NP**, but it's not known whether it's in **P**

NP = Nondeterministic polynomial time

NP is the class of languages that have polynomial time verifiers.

THEOREM

A language is in NP iff it is decided by some nondeterministic polynomial time Turing machine.

⇒ If a language is in NP, then it has a non-deterministic poly time decider

- We know: If a lang L is in NP, then it has a poly time verifier V
- Need to: create NTM deciding L :

On input $w =$

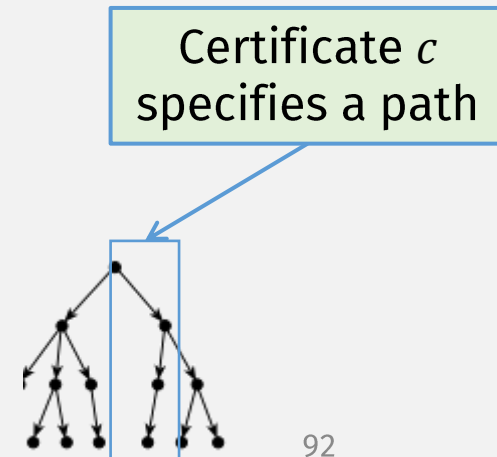
- Nondeterministically run V with w and all possible poly length certificates c

⇐ If a language has a non-deterministic poly time decider, then it is in NP

- We know: L has NTM decider N ,
- Need to: show L is in NP, i.e., create polytime verifier V :

On input $\langle w, c \rangle =$

- Convert N to deterministic TM, and run it on w , but take only one computation path
- Let certificate c dictate which computation path to follow



NP

$\text{NTIME}(t(n)) = \{L \mid L \text{ is a language decided by an } O(t(n)) \text{ time nondeterministic Turing machine}\}.$

$$\text{NP} = \bigcup_k \text{NTIME}(n^k)$$

NP = Nondeterministic polynomial time

NP VS P

Let $t: \mathcal{N} \rightarrow \mathcal{R}^+$ be a function. Define the *time complexity class*, $\text{TIME}(t(n))$, to be the collection of all languages that are decidable by an $O(t(n))$ time Turing machine.

P is the class of languages that are decidable in polynomial time on a **deterministic** single-tape Turing machine. In other words,

$$P = \bigcup_k \text{TIME}(n^k).$$

P = Deterministic polynomial time

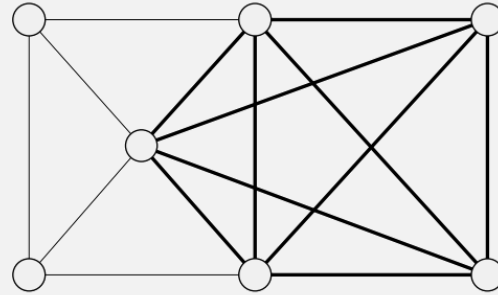
$\text{NTIME}(t(n)) = \{L \mid L \text{ is a language decided by an } O(t(n)) \text{ time } \text{non-deterministic} \text{ Turing machine}\}.$

$$\text{NP} = \bigcup_k \text{NTIME}(n^k)$$

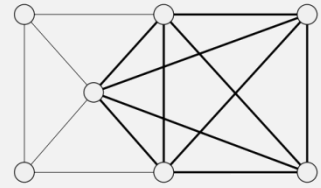
NP = Nondeterministic polynomial time

More **NP** Problems

- $CLIQUE = \{\langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique}\}$
 - A clique is a subgraph where every two nodes are connected
 - A k -clique contains k nodes



- $SUBSET-SUM = \{\langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t\}$



Theorem: *CLIQUE* is in NP

$CLIQUE = \{\langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique}\}$

PROOF IDEA The clique is the certificate.

Let $n = \#$ nodes in G

c is at most n

PROOF The following is a verifier V for *CLIQUE*.

$V =$ “On input $\langle \langle G, k \rangle, c \rangle$:

1. Test whether c is a subgraph with k nodes in G .
2. Test whether G contains all edges connecting nodes in c .
3. If both pass, *accept*; otherwise, *reject*.”

For each node in c , check whether it's in $G: O(n^2)$

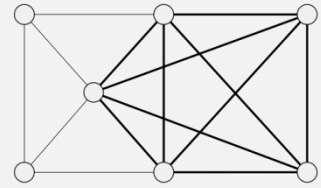
For each pair of nodes in c , check whether there's an edge in $G: O(n^2)$

A *verifier* for a language A is an algorithm V , where

$$A = \{w \mid V \text{ accepts } \langle w, c \rangle \text{ for some string } c\}.$$

We measure the time of a verifier only in terms of the length of w , so a *polynomial time verifier* runs in polynomial time in the length of w . A language A is *polynomially verifiable* if it has a polynomial time verifier.

NP is the class of languages that have polynomial time verifiers.



Proof 2: *CLIQUE* is in NP

$CLIQUE = \{ \langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique} \}$

$N =$ “On input $\langle G, k \rangle$, where G is a graph:

1. Nondeterministically select a subset c of k nodes of G .
2. Test whether G contains all edges connecting nodes in c .
3. If yes, *accept*; otherwise, *reject*.”

“try all subgraphs”

$O(n^2)$

To prove a lang L is in NP, create either a:

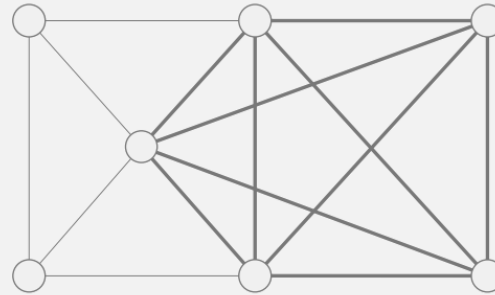
- **Deterministic** poly time **verifier**
- **Nondeterministic** poly time **decider**

THEOREM

.....
A language is in NP iff it is decided by some nondeterministic polynomial time Turing machine.

More **NP** Problems

- $CLIQUE = \{\langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique}\}$
 - A clique is a subgraph where every two nodes are connected
 - A k -clique contains k nodes



- $SUBSET-SUM = \{\langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t\}$
 - Some subset of a set of numbers S must sum to some total t
 - e.g., $\langle \{4, 11, 16, 21, 27\}, 25 \rangle \in SUBSET-SUM$

Theorem: *SUBSET-SUM* is in NP

$SUBSET-SUM = \{\langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t\}$

PROOF IDEA The subset is the certificate.

To prove a lang is in NP, create either:

- **Deterministic poly time verifier**
- **Nondeterministic poly time decider**

PROOF The following is a **verifier V** for *SUBSET-SUM*.

$V =$ “On input $\langle \langle S, t \rangle, c \rangle$:

1. Test whether c is a collection of numbers that sum to t .
2. Test whether S contains all the numbers in c .
3. If both pass, *accept*; otherwise, *reject*.”

Runtime?

Proof 2: *SUBSET-SUM* is in NP

SUBSET-SUM = $\{\langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \Sigma y_i = t\}$

To prove a lang is in NP, create either:

- Deterministic poly time verifier
- **Nondeterministic poly time decider**

ALTERNATIVE PROOF We can also prove this theorem by giving a **nondeterministic polynomial time Turing machine** for *SUBSET-SUM* as follows.

$N =$ “On input $\langle S, t \rangle$:

1. Nondeterministically select a subset c of the numbers in S .
2. Test whether c is a collection of numbers that sum to t .
3. If the test passes, *accept*; otherwise, *reject*.”

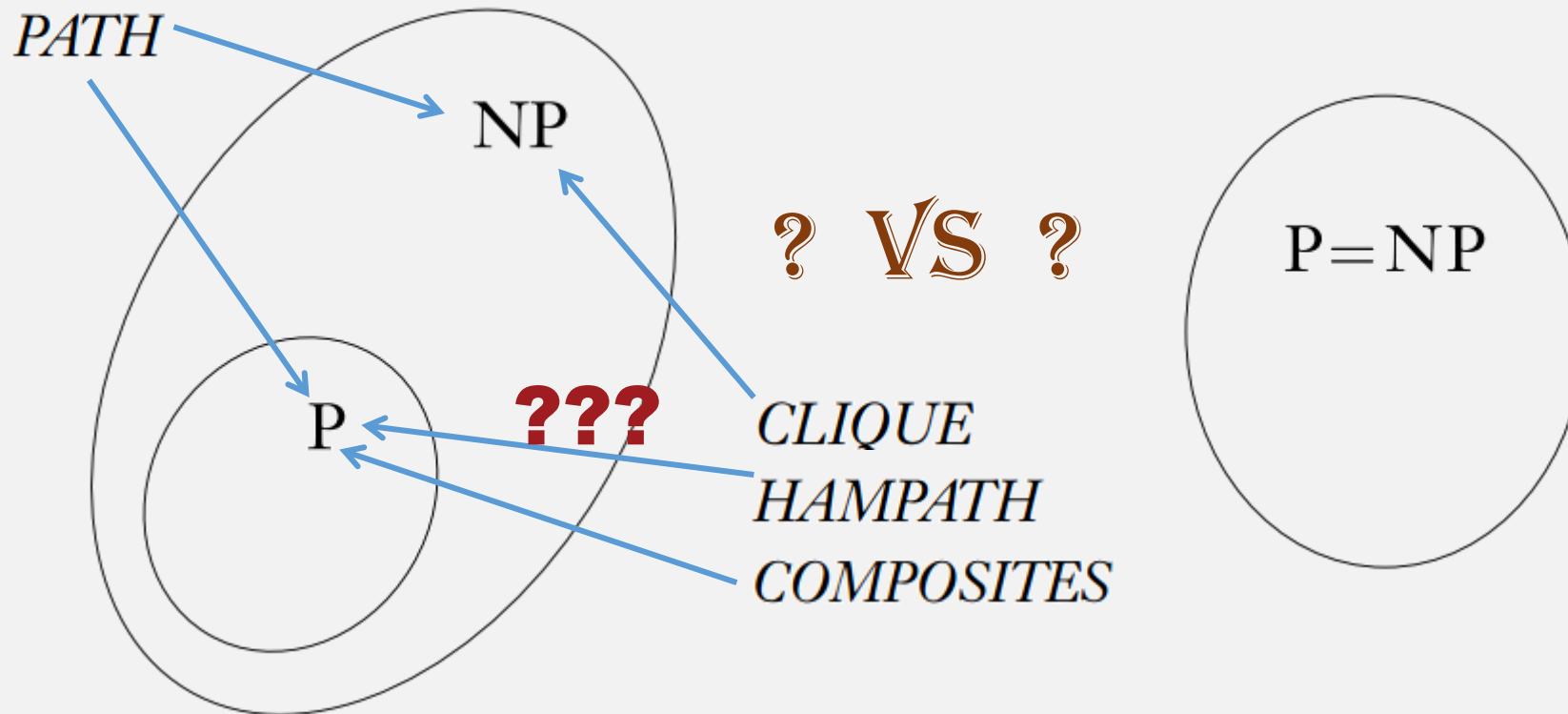
Runtime?

$$\text{COMPOSITES} = \{x \mid x = pq, \text{ for integers } p, q > 1\}$$

- A composite number is not prime
- *COMPOSITES* is polynomially verifiable
 - i.e., it's in **NP**
 - i.e., factorability is in **NP**
- A certificate could be:
 - Some factor that is not 1
- Checking existence of factors (or not, i.e., testing primality) ...
 - ... is also poly time
 - But only discovered recently (2002)!

One of the Greatest unsolved

~~HW~~ Question: Does $P = NP$?



How do you prove an algorithm doesn't have a poly time algorithm?
(in general it's hard to prove that something doesn't exist)

Implications if $P = NP$

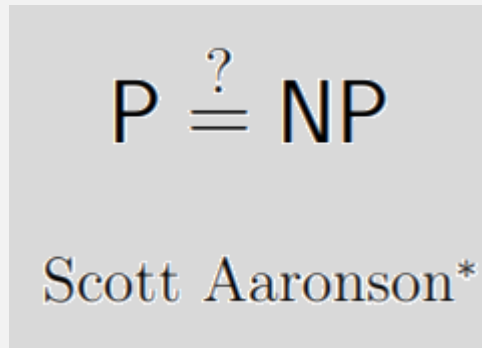
- Every problem with a “brute force” solution also has an efficient solution
- I.e., “unsolvable” problems are “solvable”
- BAD:
 - Cryptography needs unsolvable problems
 - Near perfect AI learning, recognition
- GOOD: Optimization problems are solved
 - Optimal resource allocation could fix all the world’s (food, energy, space ...) problems?

Who doesn't like niche NP jokes?



Progress on whether $P = NP$?

- Some, but still not close

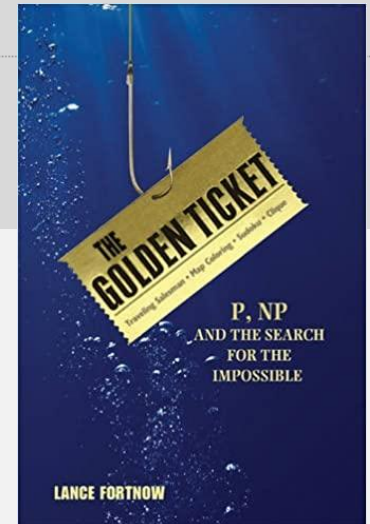


The Status of the P Versus NP Problem

By Lance Fortnow

Communications of the ACM, September 2009, Vol. 52 No. 9, Pages 78-86

10.1145/1562164.1562186



- One important concept discovered:
 - NP-Completeness

NP-Completeness

Must look at all langs, can't just look at a single lang

DEFINITION

A language B is *NP-complete* if it satisfies two conditions:

1. B is in NP, and **easy**
2. every A in NP is polynomial time reducible to B . **hard????**

- How does this help the $P = NP$ problem? **What's this?**

THEOREM

If B is NP-complete and $B \in P$, then $P = NP$.

Check-in Quiz 11/10

On gradescope